

The object of this tutorial is to build a solid object using a script, then to mesh it and solve, and finally to display the solution.

A script has the advantage that, as in this example, a solution for a generic shape can be altered and applied to others of different sizes by changing the parameter values in the script.

The object is a tee-shaped block on two soft supports. The tutorial demonstrates one method of partitioning the geometry and defining the three material properties.

```

# test program t020
# more than 2 parts, nonplanar partition
import geompy
import salome
gg = salome.ImportComponentGUI("GEOM")

# create vertices and vectors
p0 = geompy.MakeVertex(0., 0., 0.)
vectorZ = geompy.MakeVectorDXDYDZ(0., 0., 100.)
planeZ = geompy.MakePlane(p0, vectorZ, 500.)

# create boxes
box1 = geompy.MakeBoxDXDYDZ(200., 300., 420.)
box1t = geompy.MakeTranslation(box1, 0., -300., -210.)
box2 = geompy.MakeBox(-10., -300., 100., 210., -200., 220.)
box2m = geompy.MakeMirrorByPlane(box2, planeZ)
box3 = geompy.MakeBox(0., -275., 110., 200., -200., 210.)
box3m = geompy.MakeMirrorByPlane(box3, planeZ)

# assemble boxes
block1 = geompy.MakeCut(box1t, box2)
block2 = geompy.MakeCut(block1, box2m)
block3 = geompy.MakeFuse(block2, box3)
block4 = geompy.MakeFuse(block3, box3m)

# create partitions
partition1 = geompy.MakePartition([block4], [box3, box3m])

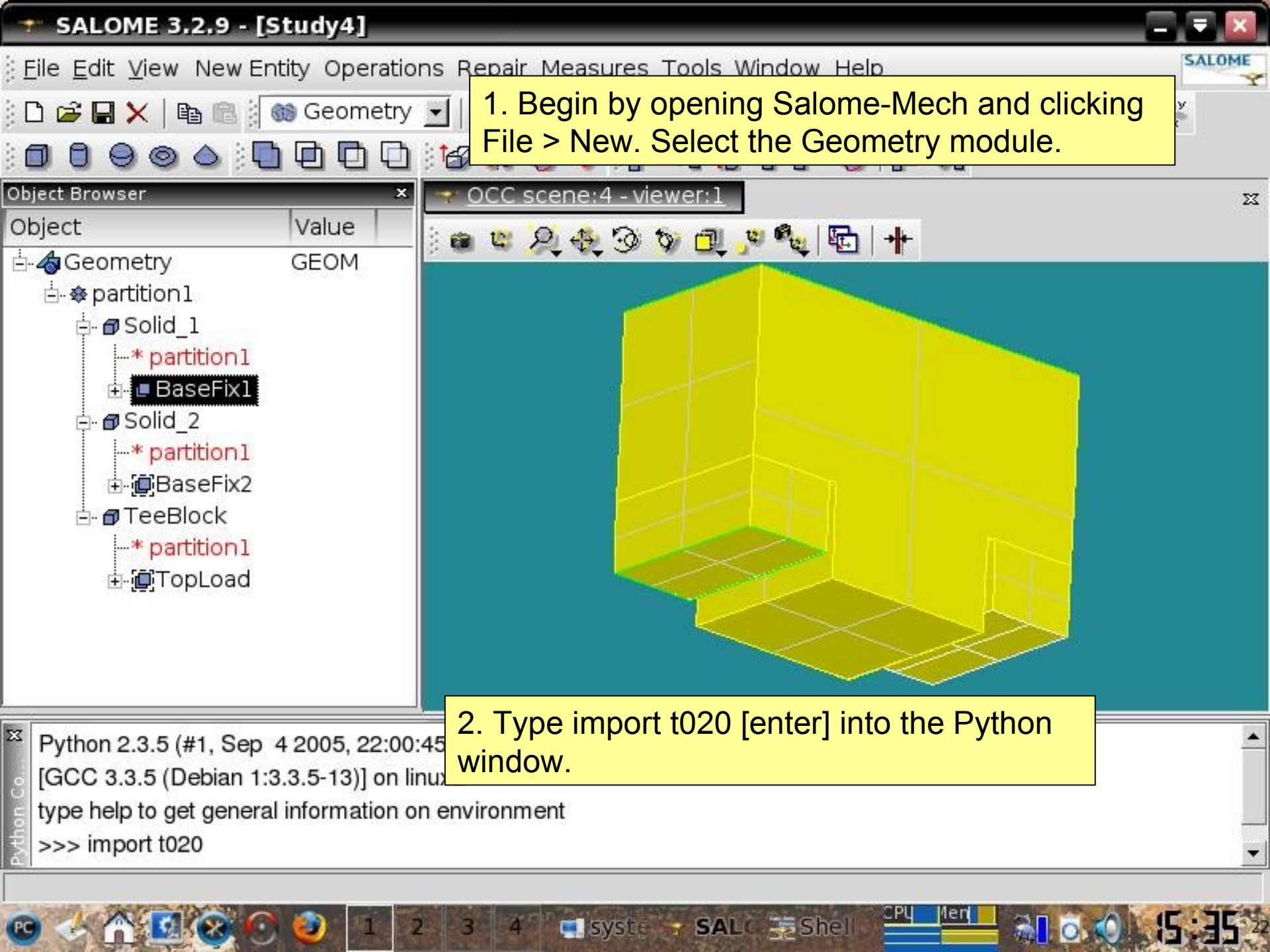
# add objects in the study
id_solid1 = geompy.addToStudy(partition1,"partition1")
# display the boxes
gg.createAndDisplayGO(id_solid1)
gg.setDisplayMode(id_solid1,1)

```

The shape is defined using a script called t020.py which creates a shape called partition1. The script file is saved to the /home folder.

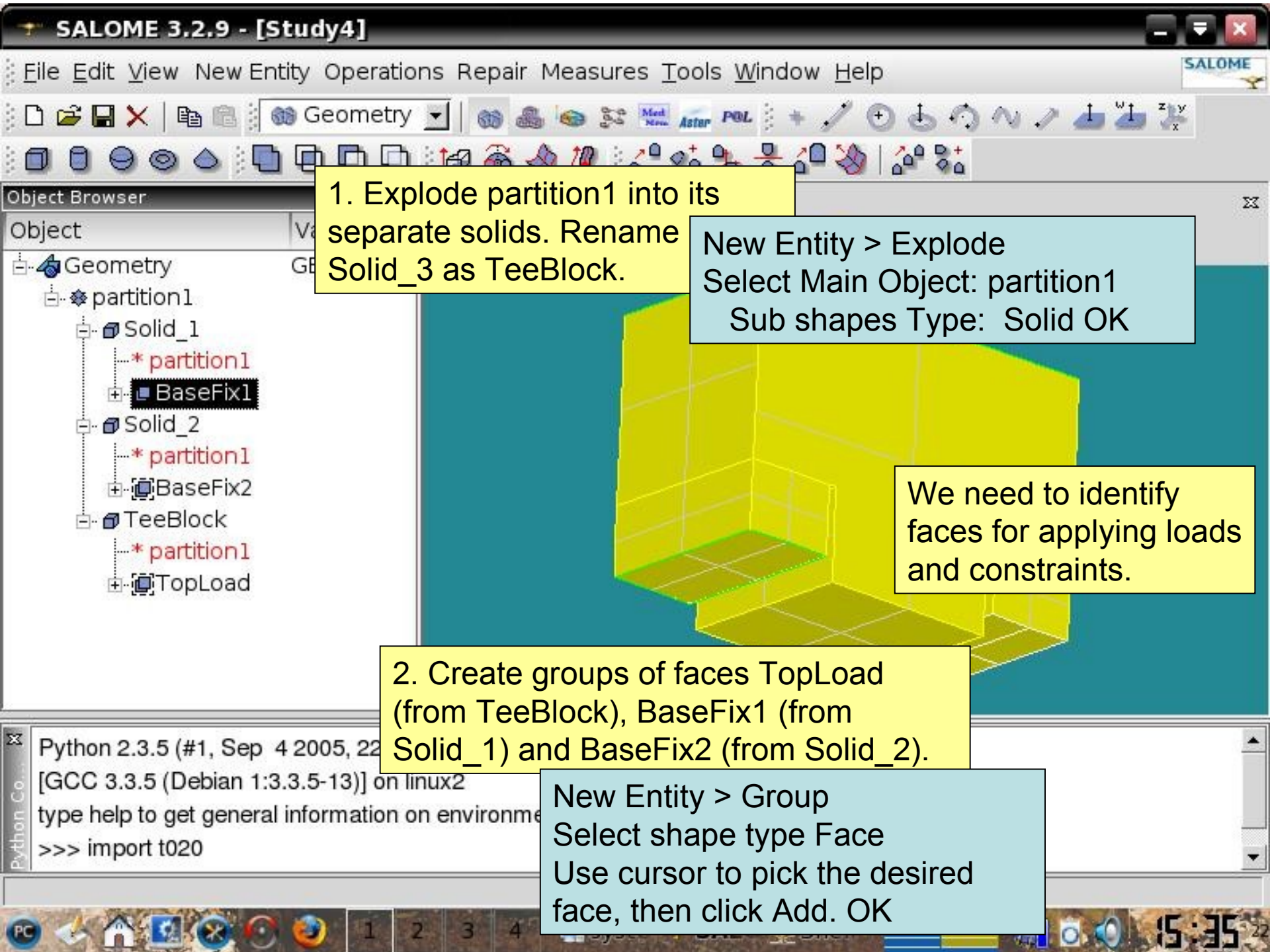
The script is written in Python, and in addition it uses special functions which are prefixed =*geompy*. These are 3D modelling tools which interact with Salome-Mech to create the geometry on which meshing and solution are based.

The functions are explained on the Salome website.



1. Begin by opening Salome-Mech and clicking File > New. Select the Geometry module.

2. Type import t020 [enter] into the Python window.



1. Explode partition1 into its separate solids. Rename Solid_3 as TeeBlock.

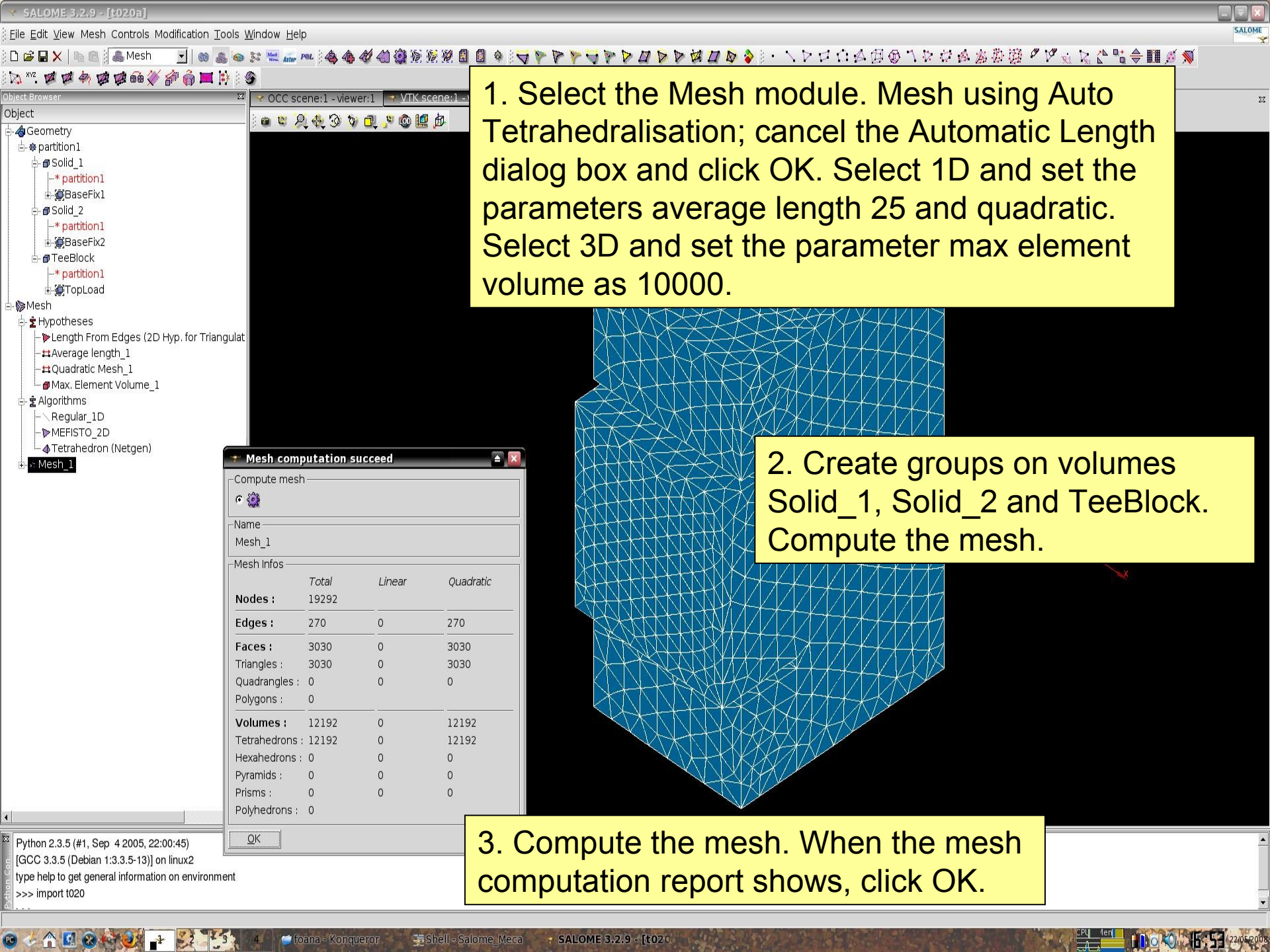
New Entity > Explode
Select Main Object: partition1
Sub shapes Type: Solid OK

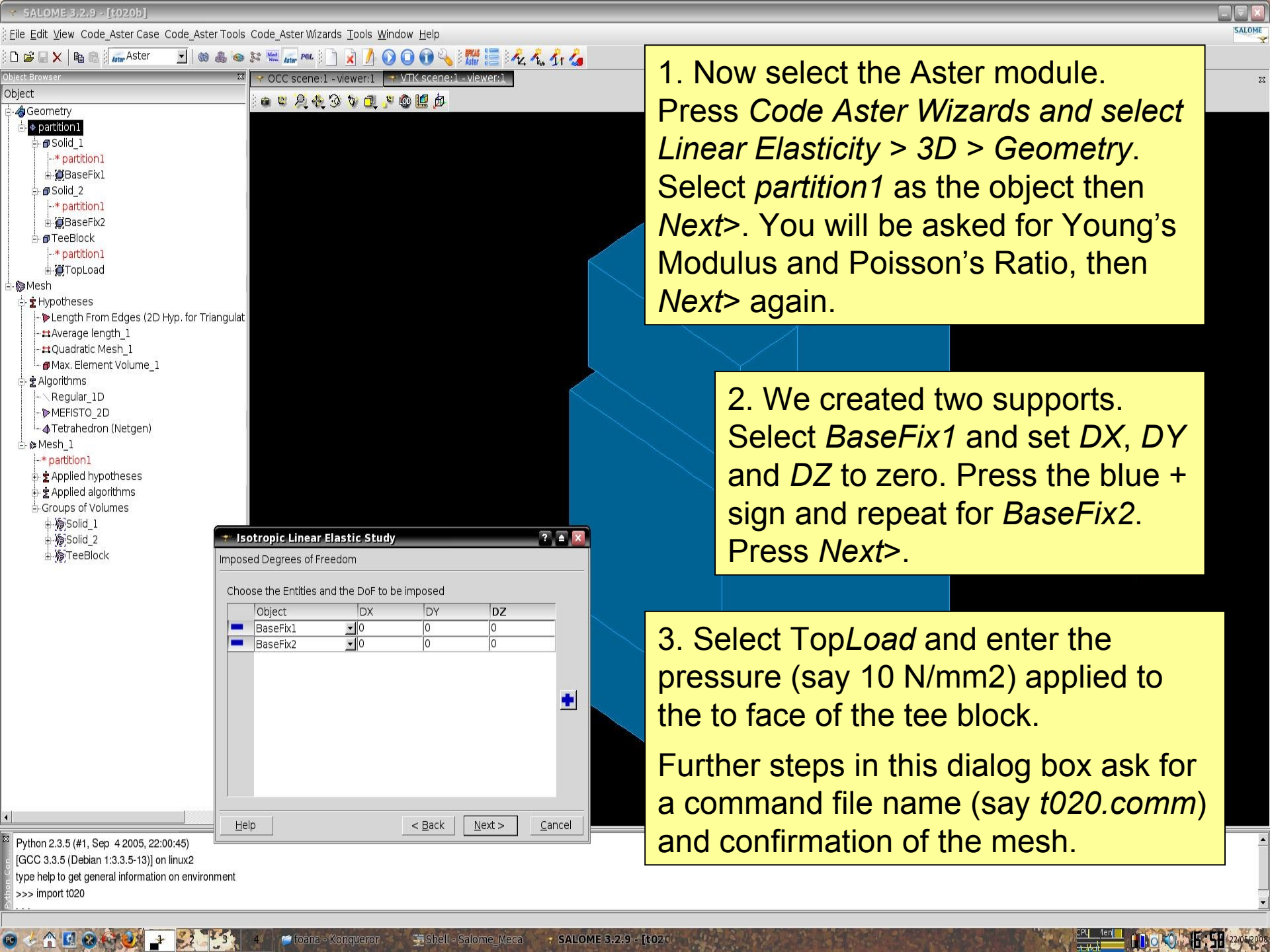
We need to identify faces for applying loads and constraints.

2. Create groups of faces TopLoad (from TeeBlock), BaseFix1 (from Solid_1) and BaseFix2 (from Solid_2).

New Entity > Group
Select shape type Face
Use cursor to pick the desired face, then click Add. OK

```
Python 2.3.5 (#1, Sep 4 2005, 22:02:02) on linux2
[GCC 3.3.5 (Debian 1:3.3.5-13)]
type help to get general information on environment
>>> import t020
```



1. Now select the Aster module. Press *Code Aster Wizards* and select *Linear Elasticity > 3D > Geometry*. Select *partition1* as the object then *Next>*. You will be asked for Young's Modulus and Poisson's Ratio, then *Next>* again.

2. We created two supports. Select *BaseFix1* and set *DX*, *DY* and *DZ* to zero. Press the blue + sign and repeat for *BaseFix2*. Press *Next>*.

3. Select *TopLoad* and enter the pressure (say 10 N/mm²) applied to the to face of the tee block.

Further steps in this dialog box ask for a command file name (say *t020.comm*) and confirmation of the mesh.

```
DEBUT();
```

```
Steel=DEFI_MATERIAU(ELAS=_F(E=200000.,  
                  NU=0.3,,);
```

```
Rubber1=DEFI_MATERIAU(ELAS=_F(E=22.5,  
                  NU=0.3,,);
```

```
Rubber2=DEFI_MATERIAU(ELAS=_F(E=45.,  
                  NU=0.3,,);
```

```
MAIL=LIRE_MALLAGE(FORMAT='MED',);
```

```
MODE=AFFE_MODELE(MALLAGE=MAIL,  
                  AFFE=_F(TOUT='OUI',  
                  PHENOMENE='MECANIQUE',  
                  MODELISATION='3D',,));
```

```
MAIL=MODI_MALLAGE(reuse =MAIL,  
                  MALLAGE=MAIL,  
                  ORIE_PEAU_3D=_F( GROUP_MA=('TopLoad',,)),  
                  );
```

```
MATE=AFFE_MATERIAU(MALLAGE=MAIL,  
                  AFFE=_F(GROUP_MA='Part_1',  
                            MATER=Rubber1,,  
                            _F(GROUP_MA='Part_2',  
                            MATER=Rubber2,,  
                            _F(GROUP_MA='Part_3',  
                            MATER=Steel,,));
```

```
CHAR=AFFE_CHAR_MECA(MODELE=MODE,  
                  DDL_IMPO=(  
                  _F(GROUP_MA='BaseFix1',  
                  DX=0,  
                  DY=0,  
                  DZ=0,,),  
                  _F(GROUP_MA='BaseFix2',  
                  DX=0,  
                  DY=0,  
                  DZ=0,,),  
                  PRES_REP=(  
                  _F(GROUP_MA='TopLoad',  
                  PRES=10,,),,);
```

The command file contains details of the loads, constraints and includes the material definition (Young's modulus and Poisson's Ratio).

Note that in the file created by Salome, the three parts are all of the same material. Edit the file as shown emboldened.

```
RESU=MECA_STATIQUE(MODELE=MODE,  
                  CHAM_MATER=MATE,  
                  EXCIT=_F(CHARGE=CHAR,,));
```

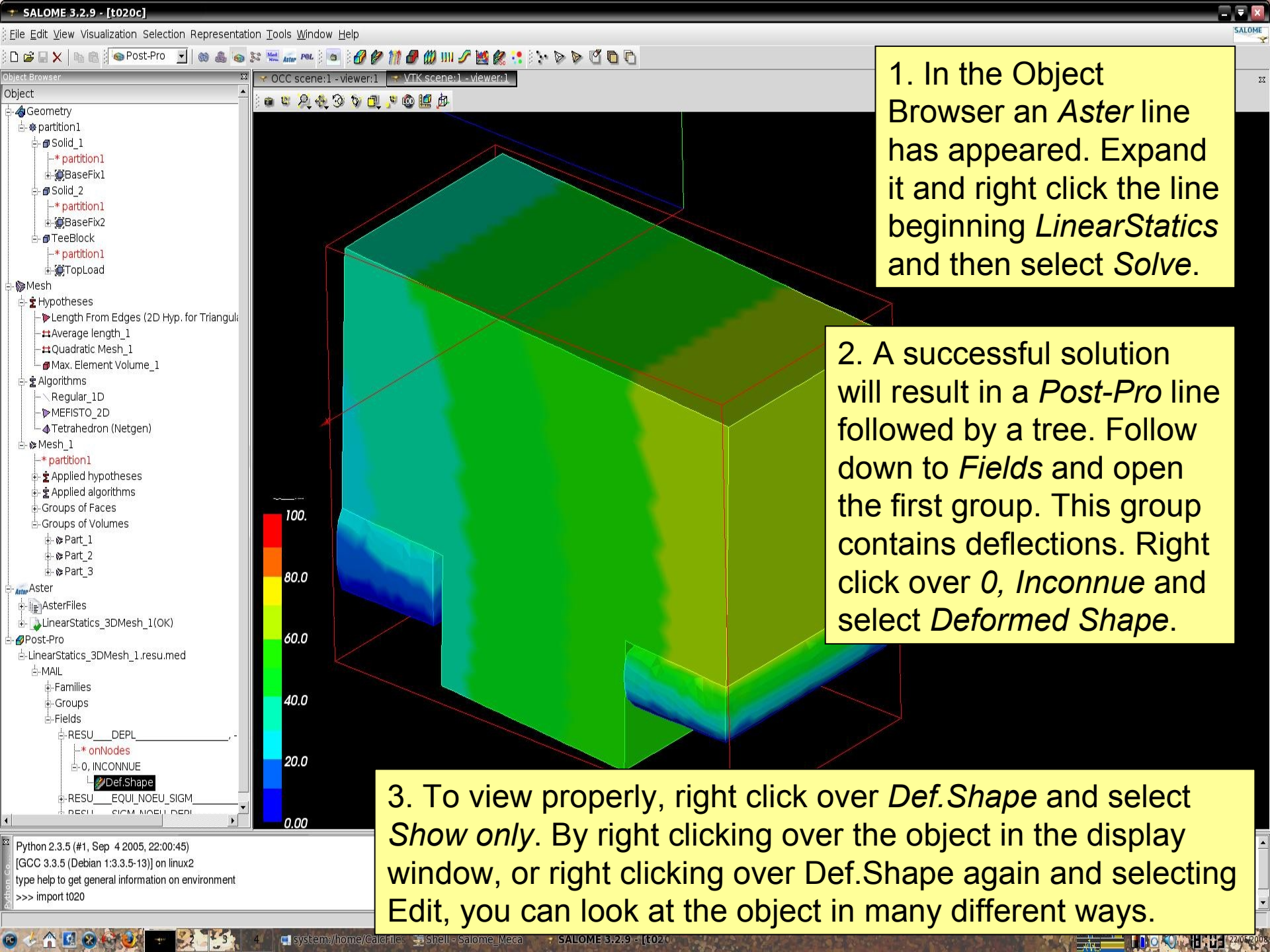
```
RESU=CALC_ELEM(reuse =RESU,  
                  MODELE=MODE,  
                  CHAM_MATER=MATE,  
                  RESULTAT=RESU,  
                  OPTION=('SIGM_ELNO_DEPL','EQUI_ELNO_SIGM',),  
                  EXCIT=_F(  
                  CHARGE=CHAR,,));
```

```
RESU=CALC_NO(reuse =RESU,  
                  RESULTAT=RESU,  
                  OPTION=('SIGM_NOEU_DEPL', 'EQUI_NOEU_SIGM', ,));
```

```
IMPR_RESU(FORMAT='MED',  
                  UNITE=80,  
                  RESU=_F(MALLAGE=MAIL,  
                  RESULTAT=RESU,
```

```
NOM_CHAM=('SIGM_NOEU_DEPL','EQUI_NOEU_SIGM','DEPL',,));
```

```
FIN();
```


```
Steel=DEFI_MATERIAU(ELAS=_F(E=200000.,  
    NU=0.3,,);
```

```
Rubber1=DEFI_MATERIAU(ELAS=_F(E=200.,  
    NU=0.3,,);
```

```
Rubber2=DEFI_MATERIAU(ELAS=_F(E=400.,  
    NU=0.3,,);
```

The deflections are rather excessive with very soft rubber pads. This is a better choice of material properties.